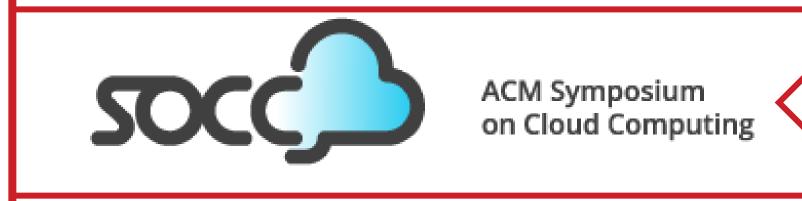
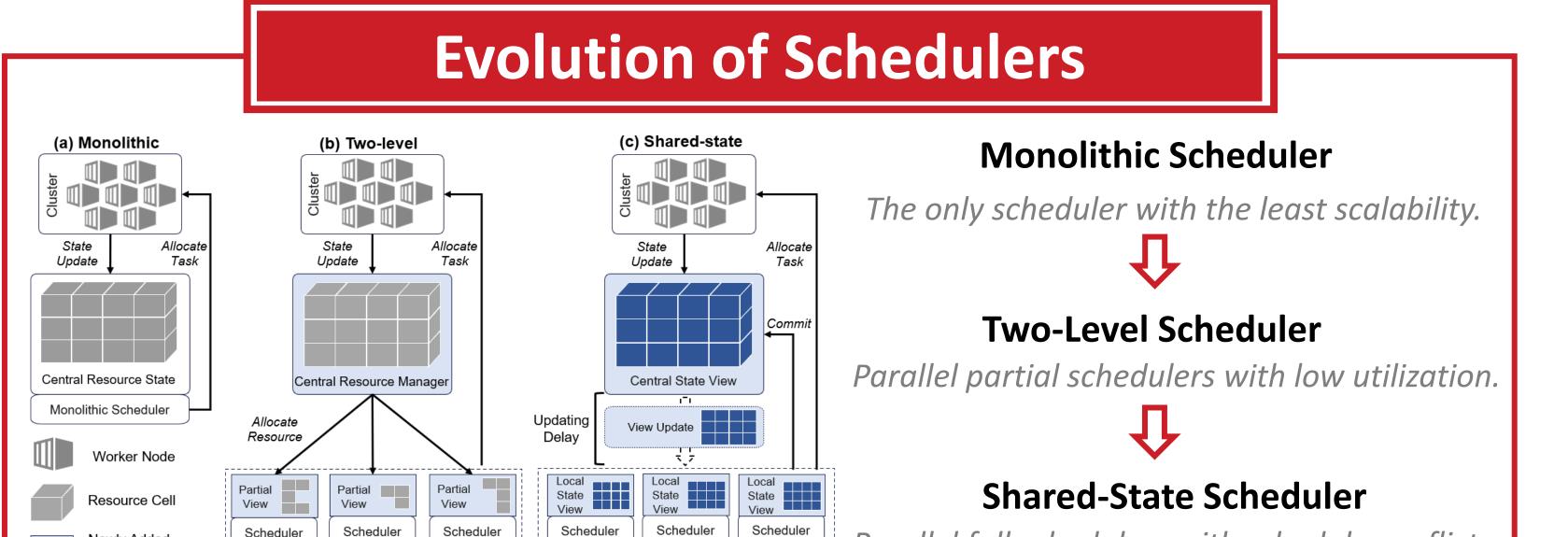


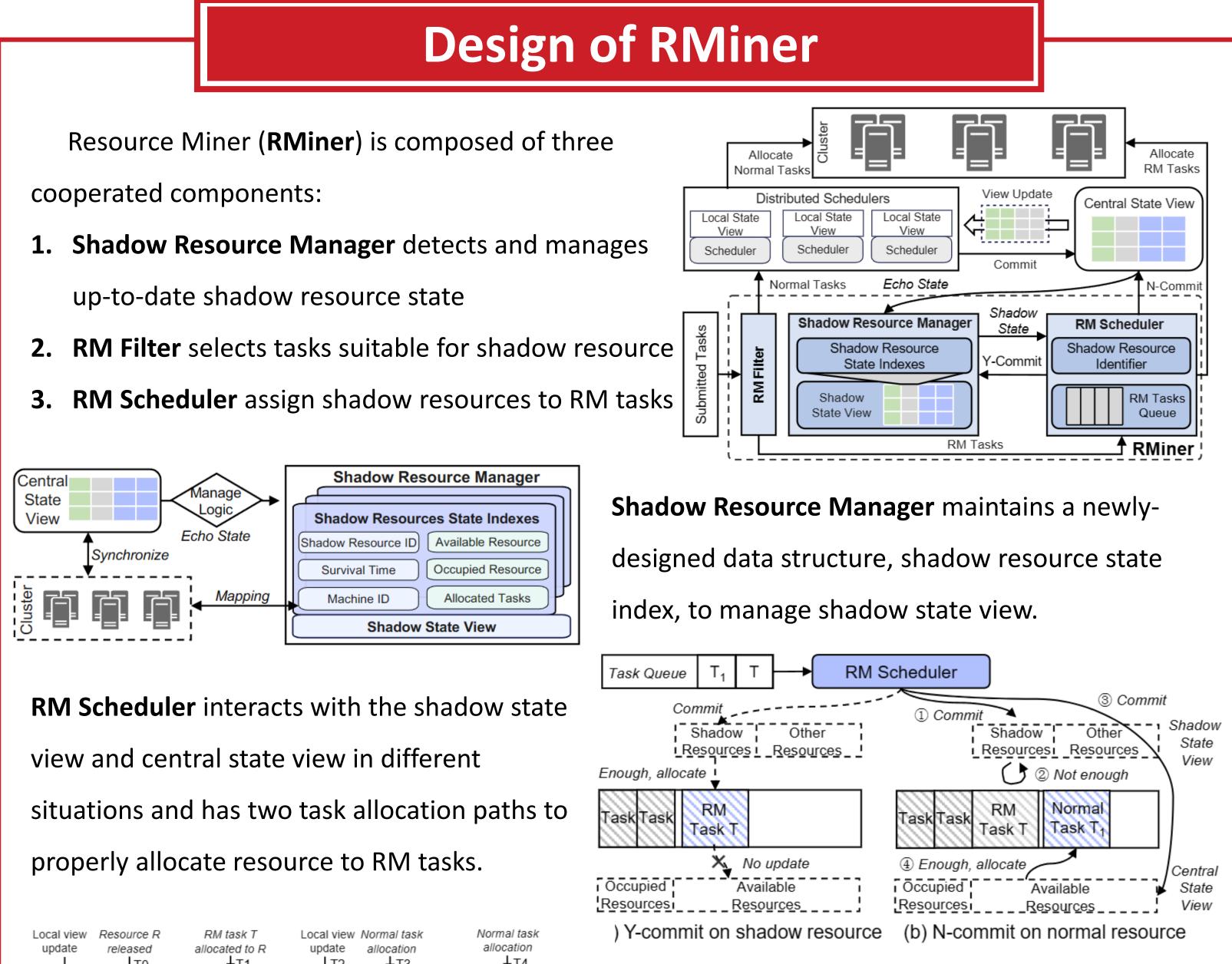
# Not All Resources are Visible



## **Exploiting Fragmented Shadow Resources in Shared-State Scheduler Architecture**

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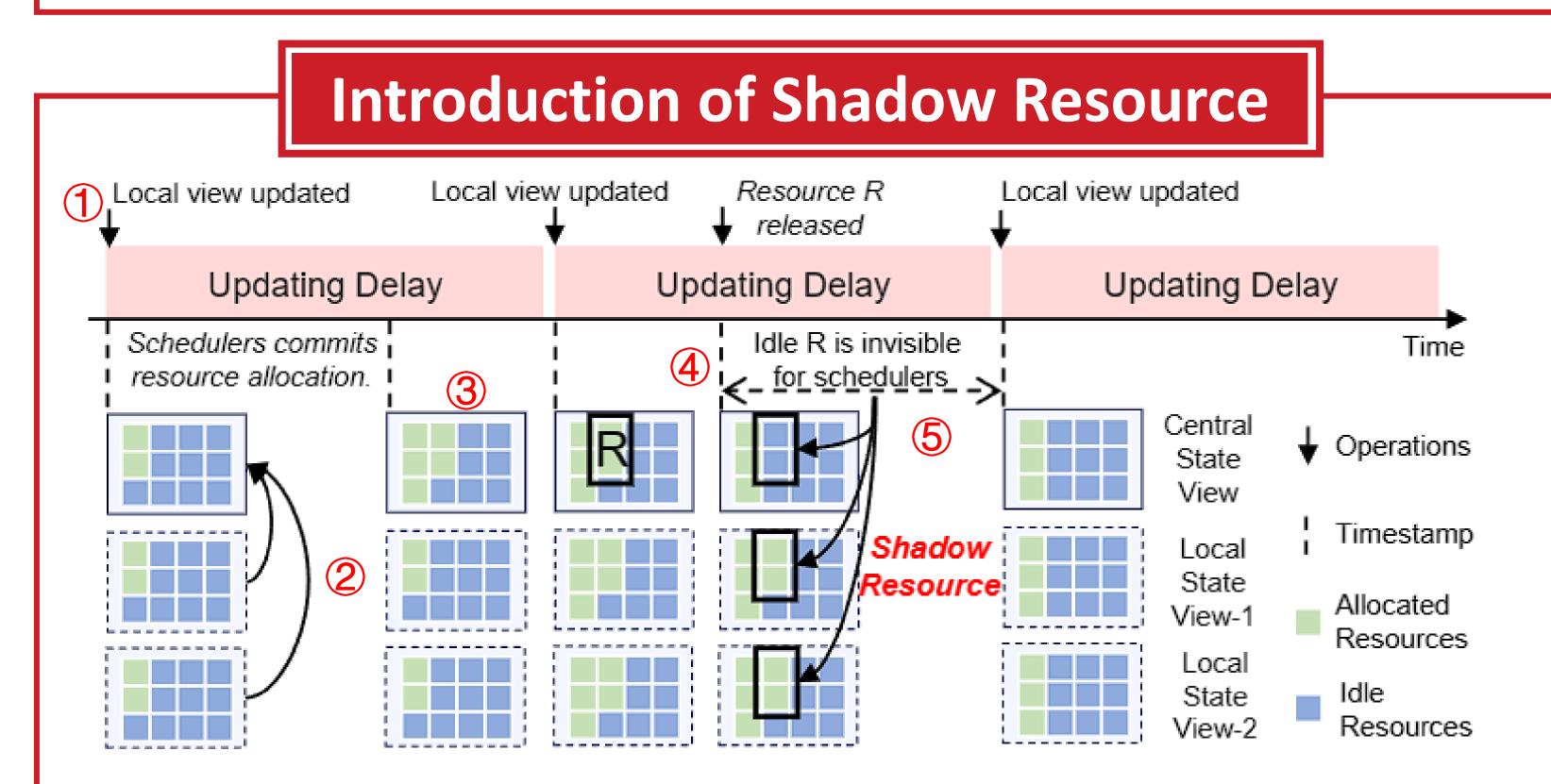






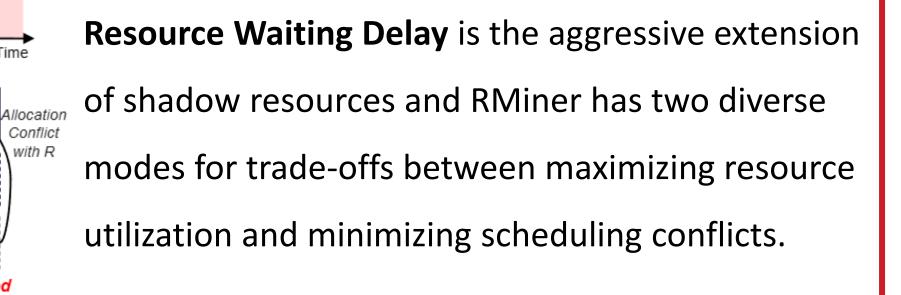
Parallel full schedulers with schedule conflicts. Distributed schedulers

Shared-state scheduler architecture has become the popular scheduling systems for large-scale clusters due to high scalability and utilization. It provides all parallel schedulers with a global view of all the resources. The central state view maintains up-to-date cluster resource status and periodically updates the local state views owned by each distributed schedulers with fixed updating delays.



1) At the start of each updating delay <sup>[5]</sup>, the Central State View (CSV) updates the local

Local view update ↓	Resource R released ↓T0	RM task T allocated to R ↓T1	Local view update ↓T2	v Normal task allocation ↓T3	Norma alloca ↓	
	Updating Delay			Updating Delay		
	Shado	w resource survival	time	Resource waiting	g delay	Tir
Shadow State View			R			
Central State View		State	2 <sub>No</sub> update		Allocation No conflict	
Local State View					2	ļ
R: Actual Invisible Shadow Resource				R: Visible Resource Still Can be Utilized		



More details and design considerations in the paper!



resource state of each Local State View (LSV) owned by distributed schedulers.

- (2) The distributed schedulers commit resource allocation decisions to CSV for task scheduling.
- 3 Within the updating delay, the latest cluster status is known by only the CSV and LSVs owned by each scheduler fall behind the actual cluster.
- (4) Similarly, when certain resources **R** are released, the CSV updates itself immediately while distributed schedulers are still relying on stale local state views.
- 5 Before the next local view update, each scheduler would treat idle resource **R** as allocated

and cannot schedule new tasks to **R**, leading to a great waste of resources.

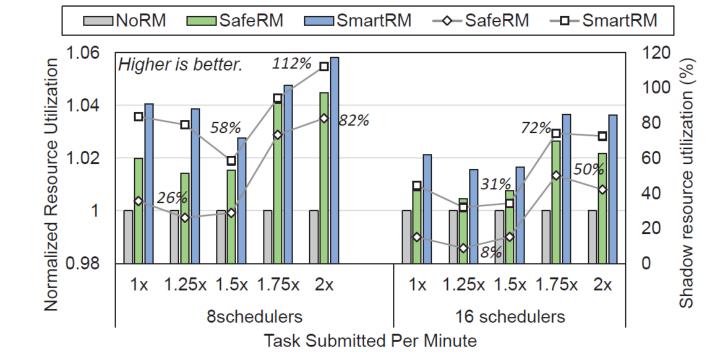
**Shadow resources** are those invisible to the distributed schedulers in their resource view when they can be used for task allocation.

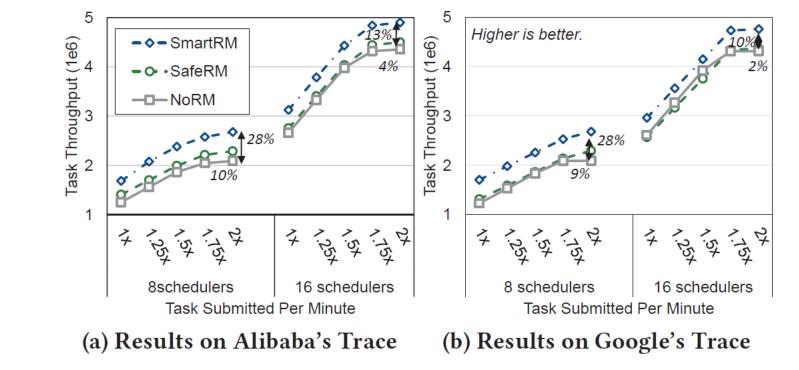
#### **Importance of Shadow Resource**

• **X**: Amount of shadow resources;  $d_u$ : Duration of updating delay  $d_u \times r_{run}$ E(X) = -•  $r_{run}$ : Total allocated resources;  $\sigma$ : Average running time of tasks  $2\sigma$ 

We both theoretically model and experimentally analyze the quantitative amount of shadow resources in the cluster. Based on industrial traces [2][3], shadow resource account for about

- **Methodology**: We modify the open-source Google cluster simulator <sup>[1]</sup> and use two industrial traces <sup>[2][3]</sup> to compare the effectiveness of RMiner with Omega <sup>[4]</sup>.
- Improvements: Resource utilization, Throughput, Job wait time





RMiner achieves ~13% throughput improvements

*RMiner achieves* ~4% *utilization improvements* via mining **31-112%** shadow resources.

- **Overheads**: Job conflicts, Scheduling Overhead
- More detailed results and analysis in the paper.

#### Takeaways

- There are invisible fragment resource opportunities in shared-state scheduling architecture.
- RMiner mines and utilizes such shadow resources to enhance the resource visibilities.
- RMiner improves cluster performance at many aspects with only minor conflict overhead. 3.

3%~12.5% in the cluster. Further, we validate the theoretical model via observing and

recording the realistic shared-state scheduling process.

Further, shadow resources are more severe nowadays due to the

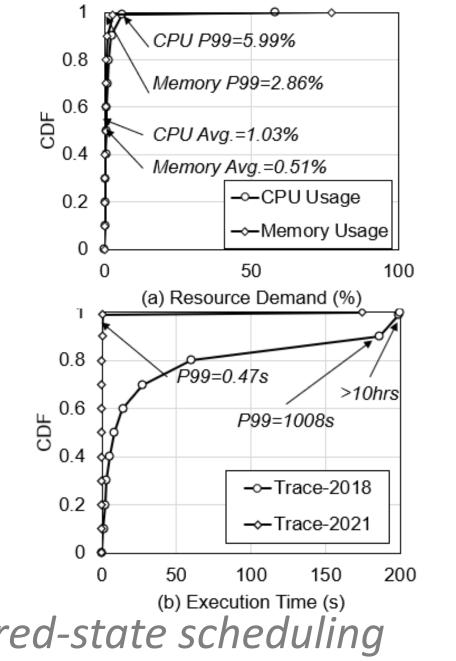
spatial and temporal granularity trends of more lightweight datacenter

tasks. It is important but challenging to properly utilize them.

- The **resource demand** of tasks is lower than traditional monolithic applications, leading to more fine-grained resource fragments.
- The execution time of tasks is decreasing due to the emergence of  $\bullet$ cloud-native technology, leading to more fleeting resource fragments.

**Shadow resources** is precious and considerable for shared-state scheduling but still requires agile management and transparent utilization.

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4. In the future, we plan to integrate RMiner into realistic shared-state scheduler systems.

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[4] Schwarzkopf, M., Konwinski, A., Abd-El-Malek, M., & Wilkes, J. (2013, April). Omega: flexible,

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